

trinity

REMOTE CONTROL FOR INDUSTRIAL ROBOT

PRODUCTION MANAGER VERSION



www.trinityrobotics.eu



The TRINITY project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 825196

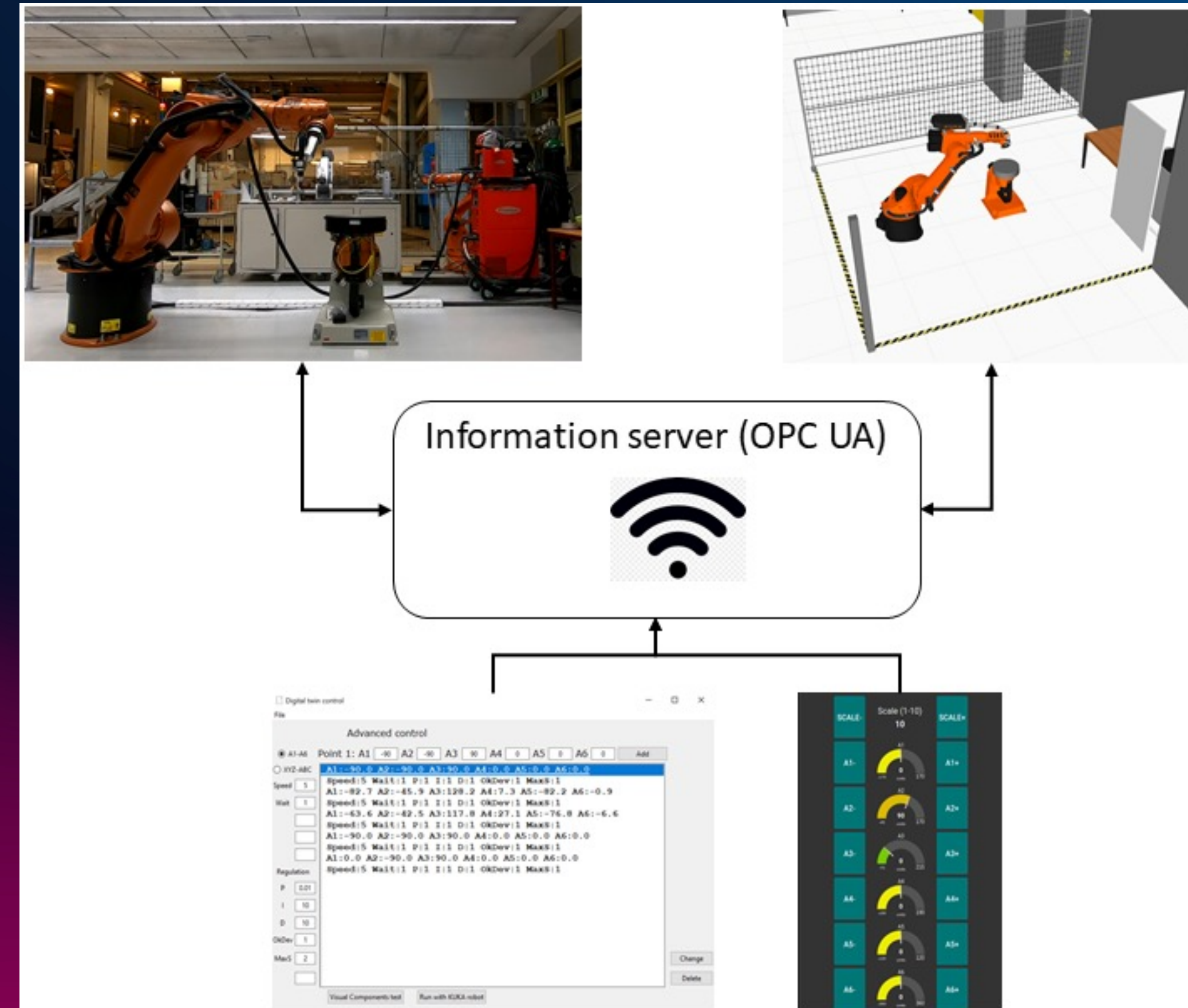
Objective of the training

- In the training lecture, you will learn and get insight into how multiple robots can be programmed through one simple interface in a general Internet browser such as Chrome. This is a crucial part of digitalization and Industry 4.0.
- The training material will also show how to set up a simple user interface for robot control.



1. Module component

- This module offers a robot controlling method through industrial internet of things (IIoT) by using an information server. A graphical user interface (GUI) takes input from the robot operator and the operator is able to program or move robots remotely
- Remote control and monitoring are usually needed in the modern industrial 4.0 factory. The module demonstrated how to control the industrial system with a platform independent interface.



2. Module environmental requirements

- The module requires the industrial information server (e.g., OPC-UA) for communication with the robots. The information server can be used for direct control of the robots and collect/monitor data from the robots.
- The module requires one server PC (can be the same one for the industrial information server) for hosting the GUI server.



3. How to integrate this system with the rest of the production line

- The module is the add-on function for previous modules. As long as the industrial information server is running as expected, the module offers a flexible GUI for the industrial system.
- Robots usually have their own robot controller, and it can be time-consuming to re-program robots with these controllers. The platform-independent GUI can be a general system that supports multiple industrial machine types from different vendors. This can allow for fast re-programming of the robots and reduce changeover time between productions.



4. Adaptability

- This module can be used in production environments with robot arms or other machines.
- The major changes for integration of the system:
 - Connect all industrial devices to the network with a central network server. (Extra controller for each of industrial devices may need)
 - Install the GUI server.



Thank you.

If you are interested in more tutorials on this module or other use cases, please follow the links in the use case lectures.



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